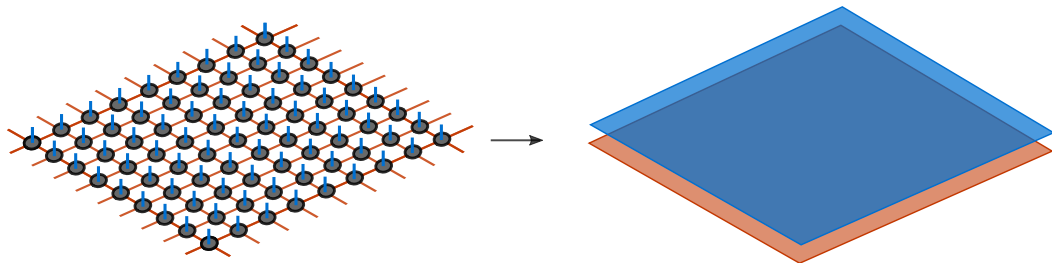


# Continuous Tensor Network States of Quantum Fields

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Max Planck Institute of Quantum Optics, Garching, Germany



GQFI seminar

Albert Einstein Institute, Potsdam, Germany

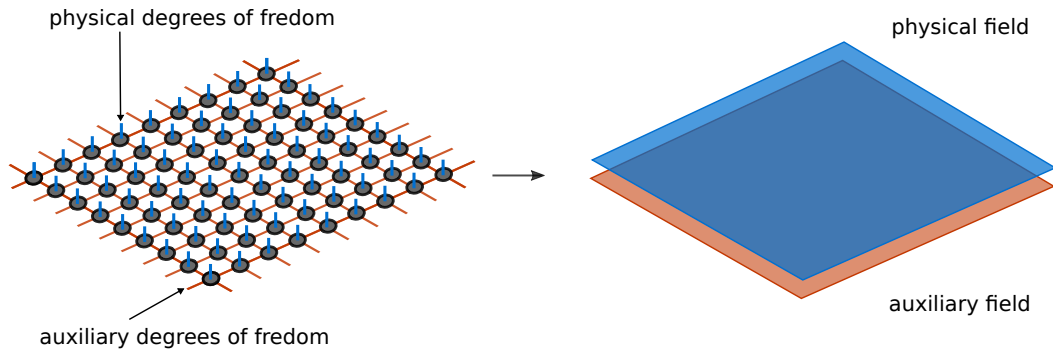
September 27th, 2018



Alexander von Humboldt  
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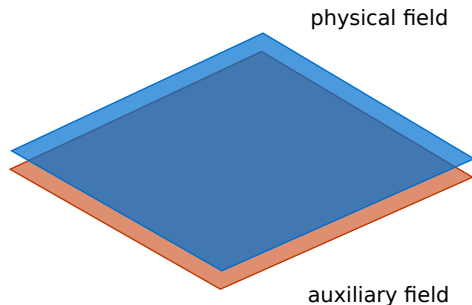
# Objective



# Objective

## Why?

- ▶ **Computations:** the continuum brings new methods (perturbative expansions, saddle point approximations, differential equations)
- ▶ **QFT:** apply directly to QFT, without discretization
- ▶ **Symmetries:** Implement Euclidean / Translation invariance exactly
- ▶ **Holography:** (?) Construct better toy models



# Problem

Many-body states are complicated.

$$|\psi\rangle = \sum_{i_1, i_2, \dots, i_n} c_{i_1, i_2, \dots, i_n} |i_1, \dots, i_n\rangle$$

$2^n$  parameters  $c_{i_1, i_2, \dots, i_n}$ .

Typical many-body Hamiltonians are simple.

$$H = \sum_{k=1}^n h_k$$

$\sim \text{const} \times n$  parameters.

# Problem

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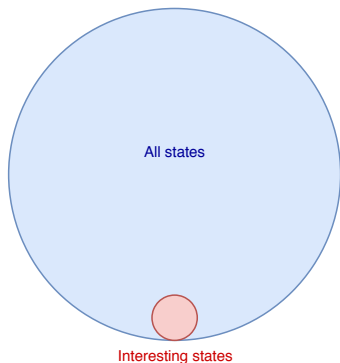
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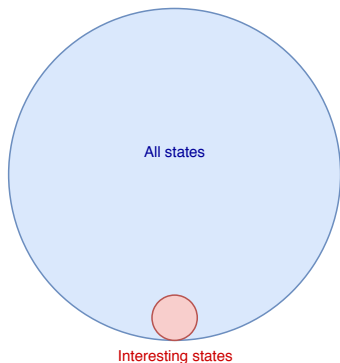


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$\sim \text{const} \times n$  parameters.

## Variational optimization

To find the ground state:

$$|\text{ground}\rangle = \min_{|\psi\rangle \in \mathcal{S}} \frac{\langle \psi | H | \psi \rangle}{\langle \psi | \psi \rangle}$$

Can we find a subspace  $\mathcal{S}$  s. t.:

- ▶  $|\mathcal{S}| \propto n^k \ll e^n$
- ▶  $\mathcal{S}$  approximates well interesting states
- ▶ *bonus*  $\langle \psi | \mathcal{O}(x) | \psi \rangle$  is computable

# An idea popular in many fields

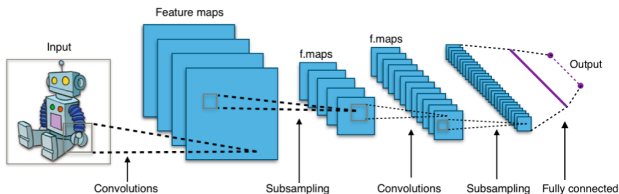
- **Mean field** approximation (of which TNS are an extension)

$$\psi(x_1, x_2, \dots, x_n) = \psi_1(x_1) \psi_2(x_2) \cdots \psi_n(x_n)$$

- Special variational wave functions in **Quantum chemistry** (whole industry of ansatz)
- **Moore-Read wavefunctions** in the study of the quantum Hall effect

$$\psi(x_1, x_2, \dots, x_n) = \left\langle \hat{\phi}(x_1) \hat{\phi}(x_2) \cdots \hat{\phi}(x_n) \right\rangle_{\text{CFT}}$$

- Fully connected and convolutional **neural networks** used in machine learning



# Matrix product states

$$|\psi\rangle = \sum_{i_1, i_2, \dots, i_n} c_{i_1, i_2, \dots, i_n} |i_1, \dots, i_n\rangle$$

## Matrix Product States (MPS)

$$|A, L, R\rangle = \sum_{i_1, i_2, \dots, i_n} \langle L | A_{i_1}(1) A_{i_2}(2) \cdots A_{i_n}(n) | R \rangle |i_1, \dots, i_n\rangle$$

- ▶  $A_i$  are  $D \times D$  complex matrices
- ▶  $A$  is a  $2 \times D \times D$  tensor  $[A_i]_{k,l}$
- ▶  $|L\rangle$  and  $|R\rangle$  are  $D$ -vectors.

**Remark:** actually equivalent with the density matrix renormalization group (DMRG)

◇  $n \times 2 \times D^2$  parameters instead of  $2^n$

◇  $D$  is the **bond dimension** and encodes the size of the variational class



## Graphical notation

$$|A, L, R\rangle = \sum_{i_1, i_2, \dots, i_n} \langle L | A_{i_1}(1) A_{i_2}(2) \cdots A_{i_n}(n) | R \rangle |i_1, \dots, i_n\rangle$$

Notation:  $[A_i]_{k,l} = \text{---} \bullet \text{---}$  and  $k \text{---} l = \sum \delta_{k,l}$  gives:

$|A, L, R\rangle =$

## Graphical notation

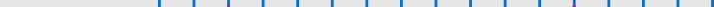
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Notation:  $[A_i]_{k,l} = \begin{array}{c} | \\ \bullet \\ \hline \end{array}$  and  $k \text{ --- } l = \sum \delta_{k,l}$  gives:

$$|A, L, R\rangle =$$


## Example: computation of correlations

$\langle A | \mathcal{O}(i_k) \mathcal{O}(i_\ell) | A \rangle =$



can be done by iteration 2 maps:

$\Phi =$   and  $\Phi_{\mathcal{O}} =$  

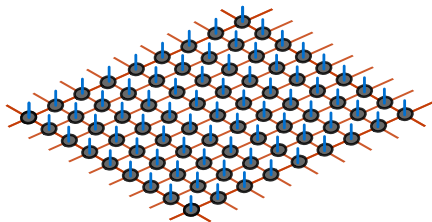
The contraction for a  $d = 1$  system, can be seen as an open-system dynamics in  $d = 0$ .

# Generalizations: different tensor networks

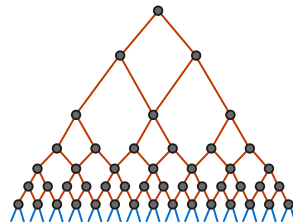
Matrix Product States (MPS)



Projected Entangled Pair States (PEPS)



Multi-scale Entanglement Renormalization Ansatz (MERA)



# Some facts

A list of theorems [very colloquially]:

- ▶ **Expressiveness** [trivial] Tensor Network States cover  $\mathcal{H}$  when  $D \propto 2^n$
- ▶ **Area law** The entanglement of a subregion of space scales as its area for a TNS
- ▶ **Efficiency** [gapped] Matrix Product States approximate well the ground states of gapped systems in 1 spatial dimension
- ▶ **Efficiency** [critical] Multi-scale Entanglement Renormalization Ansatz (MERA) approximate well the ground states of critical systems in 1 spatial dimension.
- ▶ **Symmetries** Physical symmetries can be implemented locally on the bond space
- ▶ **Inverse problem** TNS are the ground state of a local parent Hamiltonian

# Successes and limits

## Successes: why the deserved hype

- ♡ Arbitrary precision for  $1d$  quantum systems
- ♡ Classification of topological phases in  $1d$  and  $2d$
- ♡ Progress on non-Abelian lattice Gauge theories
- ♡ AdS/CFT toy models

## Limits: why it is overhyped

- ♠ Hard to contract in  $d \geq 2$
- ♠ No continuum limit in  $d \geq 2$
- ♠ Lack of analytic techniques

# Successes and limits

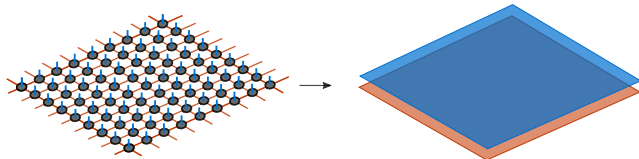
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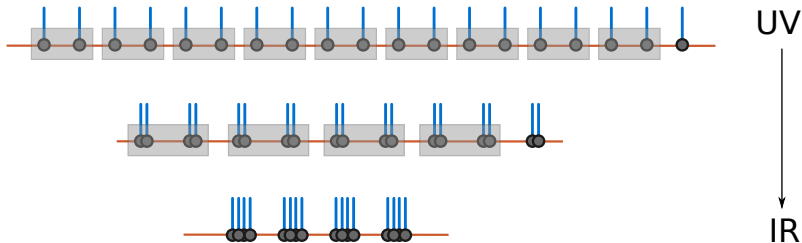
- ♠ Hard to contract in  $d \geq 2$
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*Can one apply tensor network techniques directly in the continuum, to QFT?*



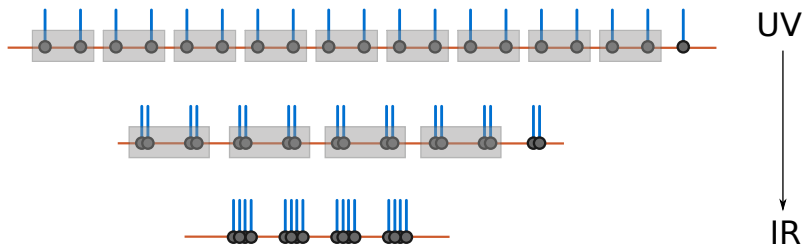
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Taking the continuum limit of a MPS



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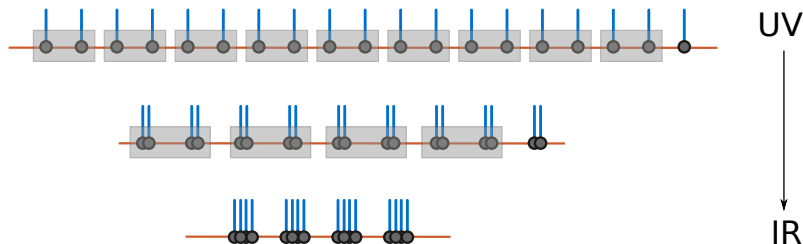


- ▶ the bond dimension  $D$  stays fixed



# Continuous Matrix Product States (cMPS)

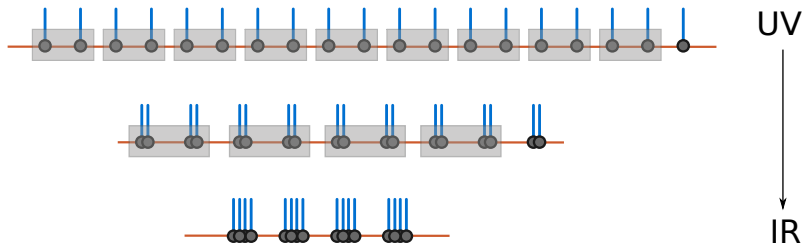
Taking the continuum limit of a MPS



- ▶ the bond dimension  $D$  stays fixed
- ▶ the local physical dimension explodes  $\mathbb{C}^2 \otimes \dots \otimes \mathbb{C}^2 \longrightarrow \mathcal{F}(L^2([x, x + dx]))$ .  
 $\implies$  **Spins** become **fields** – ( $\simeq$  central limit theorem  $\simeq$  quantum noises  $d\xi, d\xi^\dagger$ )

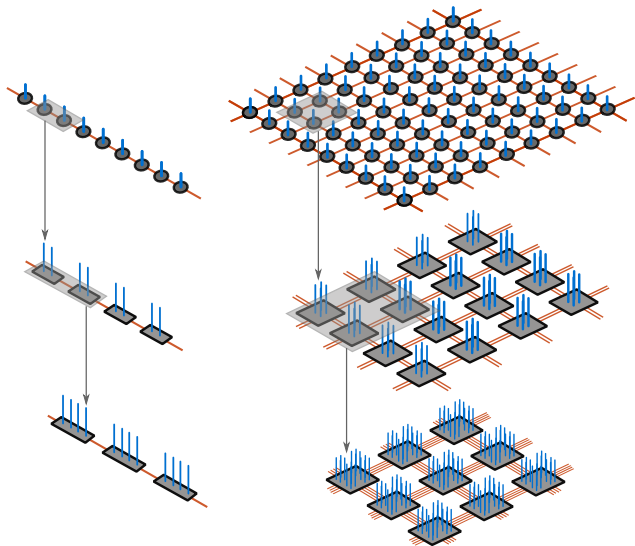
# Continuous Matrix Product States (cMPS)

Taking the continuum limit of a MPS

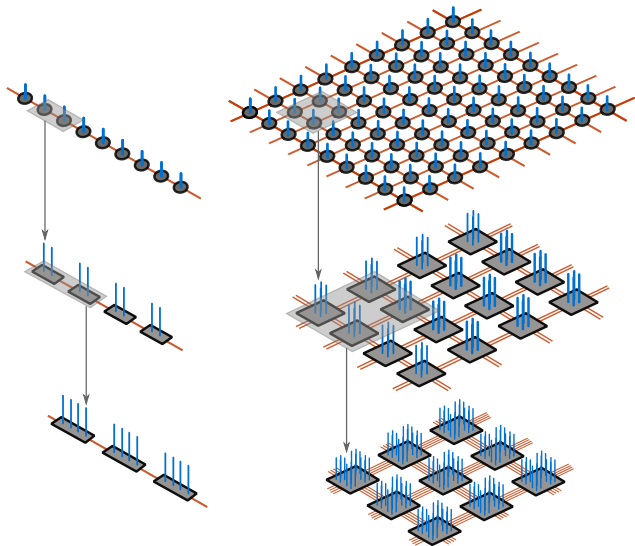


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 $\implies$  **Spins** become **fields** – ( $\simeq$  central limit theorem  $\simeq$  quantum noises  $d\xi, d\xi^\dagger$ )
- ▶ A cMPS is a quantum field state parameterized by finite dimensional matrices:  
$$|Q, R, \omega\rangle = \langle \omega_L | \mathcal{P} \exp \left\{ \int_0^L dx \, Q(x) \otimes \mathbb{1} + R(x) \otimes \psi^\dagger(x) \right\} | \omega_R \rangle | 0 \rangle$$

# Continuous Tensor Networks: blocking



# Continuous Tensor Networks: blocking



Upon blocking:

- ♣ The **physical** Hilbert space dimension  $d$  increases (idem cMPS  $\Rightarrow$  physical field)
- ♣ The **bond** dimension  $D$  increases too

# Choice of trivial tensor

For **MPS**, not much choice:



The diagram shows a horizontal orange line with a black dot in the center. A vertical blue line extends upwards from the dot. This is followed by an equals sign, then a horizontal orange line, followed by a plus sign, and finally the expression  $\epsilon \dots$ .

$$\text{---} \bullet \text{---} = \text{---} + \epsilon \dots$$

# Choice of trivial tensor

For **MPS**, not much choice:



A diagrammatic equation for Matrix Product States (MPS). On the left, a horizontal red line with a black dot in the center, and a vertical blue line extending upwards from the dot. This is followed by an equals sign, then a single horizontal red line, followed by a plus sign and an ellipsis with a blue epsilon symbol ( $\epsilon \dots$ ).

For **TNS** in  $d \geq 2$ , many options:

1. Take a  $\delta$  between all legs  $\sim$  GHZ state  $T^{(0)} =$    $\Rightarrow$  trivial geometry



# Choice of trivial tensor

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A diagrammatic equation for Matrix Product States (MPS). On the left, a horizontal red line has a black dot in the middle, with a vertical blue line segment extending upwards from the dot. This is followed by an equals sign, then a horizontal red line, followed by a plus sign, and finally the expression  $\epsilon \dots$ .

For **TNS** in  $d \geq 2$ , many options:

1. Take a  $\delta$  between all legs  $\sim$  GHZ state  $T^{(0)} =$    
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2. Take two identities  $T^{(0)} =$    
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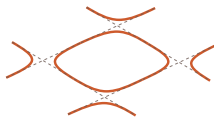
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For **MPS**, not much choice:

$$\text{---}\overset{\text{blue}}{\underset{\text{black}}{\bullet}}\text{---} = \text{---} + \varepsilon \dots$$

For **TNS** in  $d \geq 2$ , many options:

1. Take a  $\delta$  between all legs  $\sim$  GHZ state  $T^{(0)} = \text{X}$   
 $\Rightarrow$  trivial geometry
2. Take two identities  $T^{(0)} = \text{X} \text{---} \text{X}$   
 $\Rightarrow$  breakdown of Euclidean invariance
3. Take the sum of pairs of identities in both directions  $T^{(0)} = \text{X} \text{---} \text{X} + \text{X} \text{---} \text{X}$





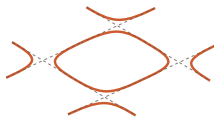
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We will consider a softer modification of the first version:

$$T^{(0)} \sim \text{X}$$

# Ansatz

1 – Take a “Trivial” tensor:

$$\begin{aligned} T_{\phi(1), \phi(2), \phi(3), \phi(4)}^{(0)} &= \text{Diagram} \\ &\sim \exp \left\{ \frac{-1}{2} \sum_{k=1}^D [\phi_k(1) - \phi_k(2)]^2 + [\phi_k(2) - \phi_k(3)]^2 \right. \\ &\quad \left. + [\phi_k(3) - \phi_k(4)]^2 + [\phi_k(4) - \phi_k(1)]^2 \right\} \end{aligned}$$

The indices  $\phi$  are in  $\mathbb{R}^D$  (and **not**  $1, \dots, D$ )

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2 – And add a “correction”:

$$\exp \left\{ -\varepsilon^2 V[\phi(1), \dots, \phi(4)] + \varepsilon^2 \alpha[\phi(1), \dots, \phi(4)] \psi^\dagger(x) \right\}$$

# Ansatz

1 – Take a “Trivial” tensor:

$$\begin{aligned} T_{\phi(1), \phi(2), \phi(3), \phi(4)}^{(0)} &= \text{Diagram with four external legs labeled } \phi(1), \phi(2), \phi(3), \phi(4) \text{ and a central dashed circle with four arrows pointing outwards.} \\ &\sim \exp \left\{ \frac{-1}{2} \sum_{k=1}^D [\phi_k(1) - \phi_k(2)]^2 + [\phi_k(2) - \phi_k(3)]^2 \right. \\ &\quad \left. + [\phi_k(3) - \phi_k(4)]^2 + [\phi_k(4) - \phi_k(1)]^2 \right\} \end{aligned}$$

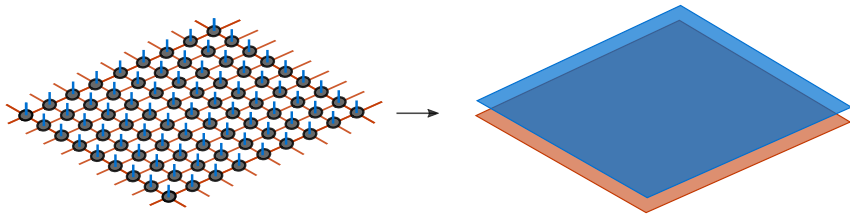
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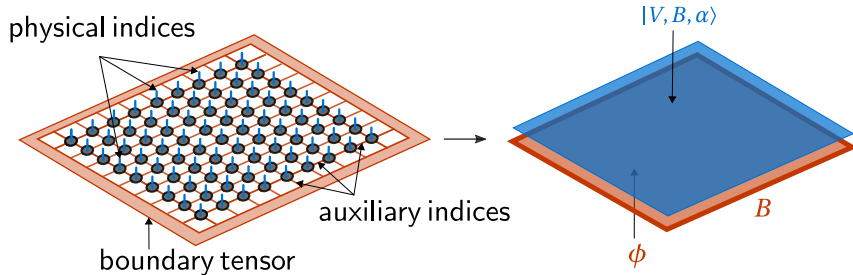
3 – Realize tensor contraction = functional integral and trivial tensor gives free field measure.

# Functional integral definition



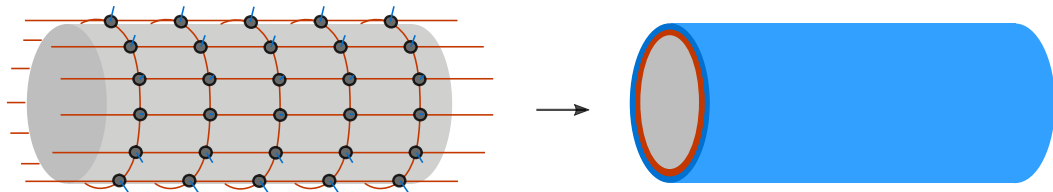
$$|V, \alpha\rangle = \int \mathcal{D}\phi \exp \left\{ - \int_{\Omega} d^d x \frac{1}{2} \sum_{k=1}^D [\nabla \phi_k(x)]^2 + V[\phi(x)] - \alpha[\phi(x)] \psi^\dagger(x) \right\} |0\rangle$$

# Functional integral definition



$$|V, B, \alpha\rangle = \int \mathcal{D}\phi \, B(\phi|_{\partial\Omega}) \exp \left\{ - \int_{\Omega} d^d x \, \frac{1}{2} \sum_{k=1}^D [\nabla \phi_k(x)]^2 + V[\phi(x)] - \alpha[\phi(x)] \psi^\dagger(x) \right\} |0\rangle$$

# Operator definition



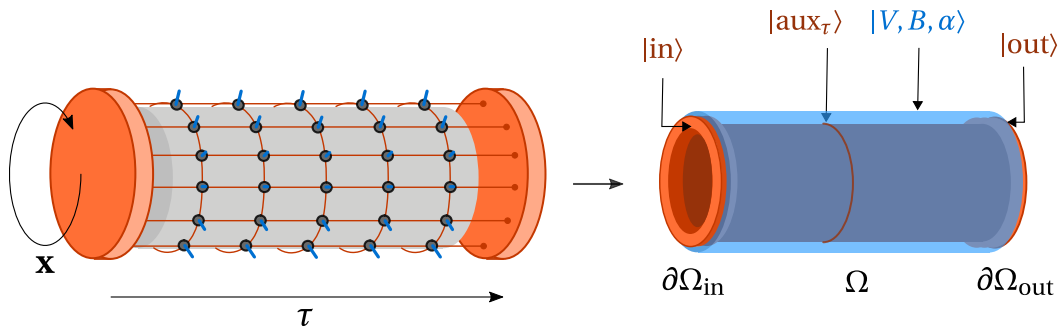
$$|V, \alpha\rangle =$$

$$\text{tr} \left[ \mathcal{T} \exp \left( - \int_0^T d\tau \int_S dx \frac{\hat{\pi}_k(x) \hat{\pi}_k(x)}{2} + \frac{\nabla \hat{\phi}_k(x) \nabla \hat{\phi}_k(x)}{2} + V[\hat{\phi}(x)] - \alpha[\hat{\phi}(x)] \psi^\dagger(\tau, x) \right) \right] |0\rangle$$

where:

- $\hat{\phi}_k(x)$  and  $\hat{\pi}_k(x)$  are  $k$  independent canonically conjugated pairs of (auxiliary) field operators:  $[\hat{\phi}_k(x), \hat{\phi}_l(y)] = 0$ ,  $[\hat{\pi}_k(x), \hat{\pi}_l(y)] = 0$ , and  $[\hat{\phi}_k(x), \hat{\pi}_l(y)] = i\delta_{k,l} \delta(x - y)$  acting on a space of  $d - 1$  dimensions.

# Operator definition



$$|V, B, \alpha\rangle =$$

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# Wave-function definition

A generic state  $|\Psi\rangle$  in Fock space can be written:

$$|\Psi\rangle = \sum_{n=0}^{+\infty} \int_{\Omega^n} \frac{\varphi_n(x_1, \dots, x_n)}{n!} \psi^\dagger(x_1) \cdots \psi^\dagger(x_n) |0\rangle$$

where  $\phi_n$  is a symmetric  $n$ -particle wave-function

## Functional integral representation

$$\varphi_n = \int d\mu(\phi) \mathcal{A}_V(\phi) \alpha[\phi(x_1)] \cdots \alpha[\phi(x_n)]$$

with:

- ▶  $d\mu(\phi) = \mathcal{D}\phi \exp \left[ -\frac{1}{2} \int_{\Omega} d^d x [\nabla \phi_k(x)]^2 \right]$
- ▶  $\mathcal{A}_V(\phi) = B(\phi|_{\partial\Omega}) \exp \left\{ - \int_{\Omega} d^d x V[\phi(x)] \right\}$

## Operator representation

$$\varphi_n =$$

$$\text{tr} \left[ \hat{B} \hat{G}_{T, \tau_n} \hat{\alpha}(x_n) \hat{G}_{\tau_n, \tau_{n-1}} \hat{\alpha}(x_{n-1}) \cdots \hat{\alpha}(x_1) \hat{G}_{\tau_1, 0} \right]$$

with:

- ▶  $\hat{G}_{u,v} = \mathcal{T} \exp \left[ - \int_v^u d\tau \int_S dx \mathcal{H}(x) \right]$
- ♡ Extension of Moore-Read

# Expressivity and stability

How big are cTNS?

## Stability

The sum of two cTNS of bond field dimension  $D_1$  and  $D_2$  is a cTNS with bond field dimension  $D \leq D_1 + D_2 + 1$ :

$$|V_1, \alpha_1\rangle + |V_2, \alpha_2\rangle = |W, \beta\rangle$$

## Expressiveness

All states in the Fock space can be approximated by cTNS:

- ▶ A field coherent state is a cTNS with  $D = 0$
- ▶ Stability allows to get all sums of field coherent states

**Note:** expressiveness can also be obtained with  $D = 1$  but it is less natural. Flexibility in  $D$  makes the expressivity higher for restricted classes of  $V$  and  $\alpha$ .

# Computations

Define generating functional for normal ordered correlation functions

$$Z_{j',j} = \frac{1}{\langle V, \alpha | V, \alpha \rangle} \langle V, \alpha | \exp \left( \int dx j'(x) \psi^\dagger(x) \right) \exp \left( \int dx j(x) \psi(x) \right) | V, \alpha \rangle$$

## Functional integral representation

- Use formula for overlap of field coherent states

$$\langle \beta | \alpha \rangle = \exp \left( \int dx \beta^*(x) \alpha(x) \right)$$

- Compute with Gaussian integration + Feynman diagrams or Monte Carlo

## Operator representation

Similar to cMPS

- Transfer matrix

$$\langle \mathcal{O}(x) \mathcal{O}(y) \rangle = \text{tr} \left( \Phi_{\mathcal{O}} \cdot e^{-(y-x)T} \Phi_{\mathcal{O}} \cdot \rho_{\text{stat}} \right)$$

with  $T = Q \otimes \mathbb{1} + \mathbb{1} \otimes \bar{Q} + R \otimes \bar{R}$  with

$$Q = - \int \frac{\hat{\pi}_k(x)^2 + [\nabla \hat{\phi}_k(x)]^2}{2} + V(\hat{\phi}(x))$$

and  $R \otimes \bar{R} = \int V(\hat{\phi}(x)) \otimes V(\hat{\phi}(x))^\dagger$

# Redundancies

## Discrete redundancy

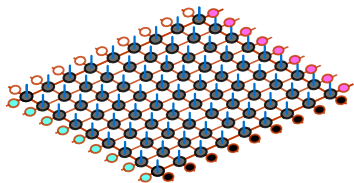
Different elementary tensors are **equivalent**, they give the same state:



when  =  and  = 

Diagram illustrating the equivalence of two elementary tensors. The left tensor is a black dot with four orange lines (two horizontal, two vertical) and a blue line pointing up. The right tensor is a black dot with four orange lines (two horizontal, two vertical) and a blue line pointing up, with a pink dot on the top horizontal line and a green dot on the bottom horizontal line. A tilde symbol ( $\sim$ ) is between them.

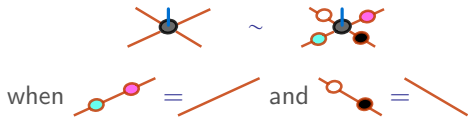
up to **boundary** terms:



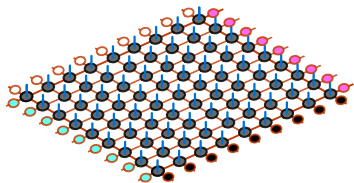
# Redundancies

## Discrete redundancy

Different elementary tensors are **equivalent**, they give the same state:



up to **boundary** terms:

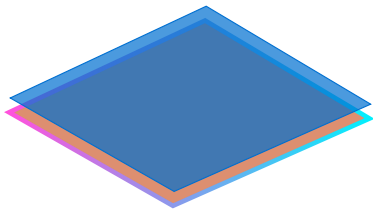


## Continuum redundancy

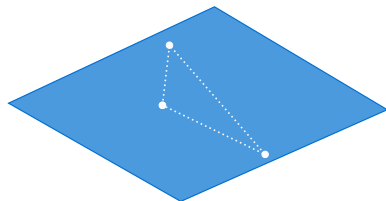
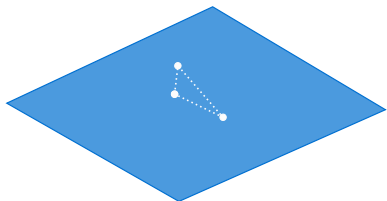
$$V(\phi) \rightarrow V(\phi) + \nabla \cdot \mathcal{F}[x, \phi(x)]$$

Just Stokes' theorem. If  $\Omega$  has a boundary  $\partial\Omega$ :

$$\mathcal{D}[\phi] \rightarrow \mathcal{D}[\phi] \exp \left\{ \oint_{\partial\Omega} d^{d-1}x \mathcal{F}[x, \phi(x)] \cdot \mathbf{n}(x) \right\}$$



# Renormalization

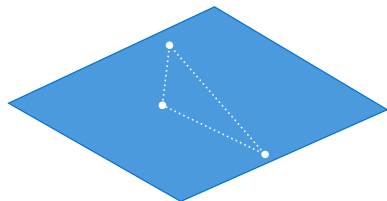
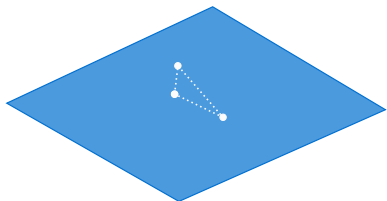


$$C(x_1, \dots, x_n) = \langle T(1) | \mathcal{O}(x_1) \cdots \mathcal{O}(x_n) | T(1) \rangle,$$

the objective is to find a tensor  $T(\lambda)$  of new parameters such that:

$$C(\lambda x_1, \dots, \lambda x_n) \propto \langle T(\lambda) | \mathcal{O}(x_1) \cdots \mathcal{O}(x_n) | T(\lambda) \rangle.$$

# Renormalization



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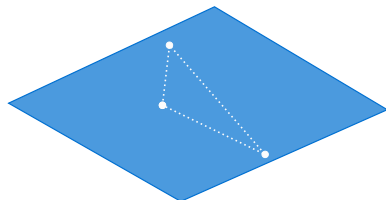
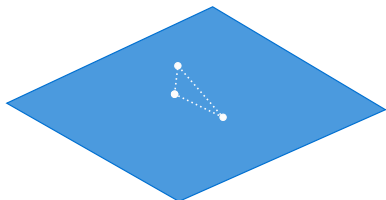
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Doable exactly:

$$V \rightarrow \lambda^d V \circ \lambda^{\frac{2-d}{2}} \quad \text{and} \quad \alpha \rightarrow \lambda^{\frac{d}{2}} \alpha \circ \lambda^{\frac{2-d}{2}}$$

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- $d = 2$ , All powers of the field in  $V$  and  $\alpha$  yield relevant couplings
- $d = 3$ , The powers  $p = 1, 2, 3, 4, 5$  of the field in  $V$  yield relevant  $\Delta > 0$  couplings.  $p = 6$  is marginal in  $V$ . For  $\alpha$ ,  $p = 1, 2$  are relevant and  $p = 3$  is marginal. All other  $p$  are irrelevant.



# Getting back cMPS

One can get back cMPS with finite bond dimension by:

1. **Compactification** Take  $d - 1$  dimensions out of  $d$  to be very small



$$|V, B, \alpha\rangle \simeq \text{tr} \left[ \hat{B} \mathcal{T} \exp \left( - \int_0^T d\tau \sum_{k=1}^D \frac{\hat{P}_k^2}{2} + V[\hat{X}] - \alpha[\hat{X}] \psi^\dagger(\tau) \right) \right] |0\rangle$$

$\Rightarrow$  Hilbert space of a quantum particle in  $D$  space dimensions.

2. **Quantization** Take  $V$  with  $D$  deep minima to force the auxiliary field to take only  $D$  possibilities

# Generalization

For a general Riemannian manifold  $\mathcal{M}$  with boundary  $\partial\mathcal{M}$ , define:

$$|V, B, \alpha\rangle = \int \mathcal{D}\phi \, B(\phi|_{\partial\mathcal{M}}) \exp \left\{ - \int_{\mathcal{M}} d^d x \sqrt{g} \left( \frac{g^{\mu\nu} \partial_\mu \phi_k \partial_\nu \phi_k}{2} + V[\phi, \nabla\phi] - \alpha[\phi, \nabla\phi] \psi^\dagger \right) \right\} |0\rangle$$

i.e. add curvature and possible anisotropies in  $V$  and  $\alpha$

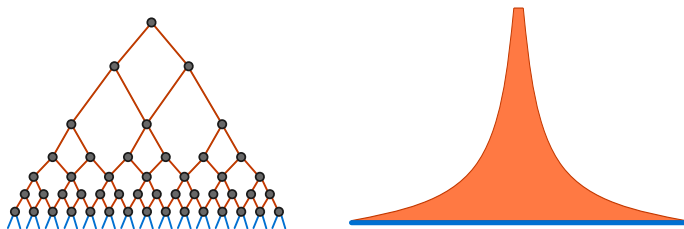
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i.e. add curvature and possible anisotropies in  $V$  and  $\alpha$

**Example:**  $\alpha[x, \phi, \nabla\phi]$  localized on the boundary and hyperbolic metric  $g$ :



→ **cMERA** in  $d-1$  dimensions

# Future

## Limitations and work for the future

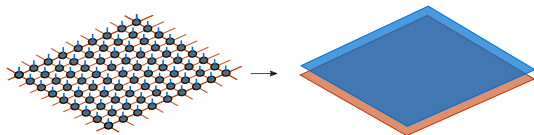
- ▶ Quite formal out of the Gaussian regime (back to perturbative)
- ▶ Limited to bosonic field theories (so far)
- ▶ Parent Hamiltonian?
- ▶ Gauge invariant states
- ▶ Topology?

# Summary

$$|V, B, \alpha\rangle = \int \mathcal{D}\phi \, B(\phi|_{\partial\Omega}) \exp \left\{ - \int_{\Omega} d^d x \, \frac{1}{2} \sum_{k=1}^D [\nabla \phi_k(x)]^2 + V[\phi(x)] - \alpha[\phi(x)] \psi^\dagger(x) \right\} |0\rangle$$

Continuous tensor network states are natural continuum limits of tensor network states and natural higher  $d$  extensions of continuous matrix product states.

1. Obtained from discrete tensor networks
2. Can be made Euclidean invariant
3. Have functional and operator representations
4. Have a geometrical equivalent of the discrete gauge redundancies
5. Have an exact and explicit “renormalization” flow



# Continuous Matrix Product States

## Type of ansatz

- ▶ Matrices  $A_{i_k}(x)$  where the index  $i_k$  corresponds to  $\psi^{\dagger i_k}(x)|0\rangle$  in physical space.

## Informal cMPS definition

$$A_0 = \mathbb{1} + \varepsilon Q$$

$$A_1 = \varepsilon R$$

$$A_2 = \frac{(\varepsilon R)^2}{\sqrt{2}}$$

...

$$A_n = \frac{(\varepsilon R)^n}{\sqrt{n}}$$

...

so we go from  $\infty$  to 2 matrices

Fixed by:

- ▶ Finite particle number

$$\begin{array}{cccccc} 0 & 0 & 0 & 0 & 0 & 0 \\ | & | & | & | & | & | \\ \square & \square & \square & \square & \square & \square \end{array} \propto 1$$

$$\begin{array}{cccccc} 0 & 1 & 0 & 0 & 0 & 0 \\ | & | & | & | & | & | \\ \square & \square & \square & \square & \square & \square \end{array} \propto \varepsilon$$

- ▶ Consistency

$$\begin{array}{cc} 1 & 1 \\ | & | \\ \square & \square \end{array} \approx \begin{array}{cc} 2 & 0 \\ | & | \\ \square & \square \end{array}$$

# Continuous Matrix Product States

## Definition

$$|Q, R, \omega\rangle = \langle \omega_L | \mathcal{P} \exp \left\{ \int_0^L dx \, Q \otimes \mathbb{1} + R \otimes \psi^\dagger(x) \right\} | \omega_R \rangle | 0 \rangle$$

- ▶  $Q, R$  are  $D \times D$  matrices,
- ▶  $|\omega_L\rangle$  and  $|\omega_R\rangle$  are boundary vectors  $\in \mathbb{C}^D$ ,
- ▶  $[\psi(x), \psi^\dagger(y)] = \delta(x - y)$

## Idea:

$$\begin{aligned} A(x) &\simeq A_0 \mathbb{1} + A_1 \psi^\dagger(x) \\ &\simeq \mathbb{1} \otimes \mathbb{1} + \varepsilon Q \otimes \mathbb{1} + \varepsilon R \otimes \psi^\dagger(x) \\ &\simeq \exp \left[ \varepsilon \left( Q \otimes \mathbb{1} + R \otimes \psi^\dagger(x) \right) \right] \end{aligned}$$

## Computations

Thermodynamic limit

$$\langle \mathcal{O}(x) \mathcal{O}(y) \rangle = \text{tr} \left( \Phi_{\mathcal{O}} \cdot e^{-(y-x)T} \Phi_{\mathcal{O}} \cdot \rho_{\text{stat}} \right)$$

$$\text{with } T = Q \otimes \mathbb{1} + \mathbb{1} \otimes \bar{Q} + R \otimes \bar{R}$$